

Optimal dividend strategies for a catastrophe insurer

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(joint with P. Azcue[†] and N. Muler)

Outline

- ▶ Dividend problem in insurance
 - ▶ Rich source for stochastic control problems
 - ▶ Non-standard problem formulations

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- ▶ Dividend problem in insurance
 - ▶ Rich source for stochastic control problems
 - ▶ Non-standard problem formulations
- ▶ Shot-noise Cox process for claim arrivals
 - ↪ Motivation from **Catastrophe Insurance**
- ▶ Solve two-dimensional control problem
- ▶ Numerical Illustrations / Interpretations

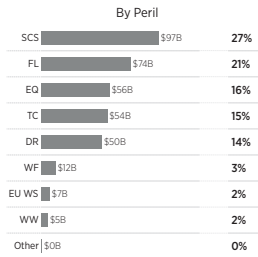
Natural catastrophes: Severe convective storms



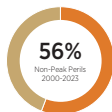
Simulated tornado-producing supercell (30m resolution, EF5 near El Reno and Oklahoma City, 2011)

Orf et al. (2017)

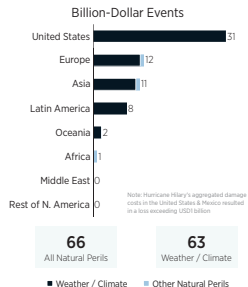
Natural catastrophes: Economic Losses 2023



Peak / Non-Peak Perils



■ Peak ■ Non-Peak



EQ: Earthquake

DR: Drought

SCS: Severe Convective Storm

EU WS: European Windstorm

TC: Tropical Cyclone

WF: Wildfire

WW: Winter Weather

FL: Flooding

Gallagher Re: NatCat & Climate Report 2023

Natural catastrophes: Comparison 2023 (in bn. USD)

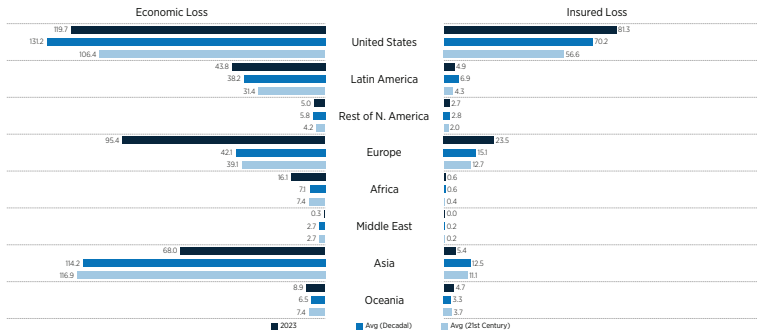


Figure 9: Regional economic and insured losses in 2023 versus recent history | Data and Graphic: Gallagher Re

Gallagher Re: NatCat & Climate Report 2023

► Climate Change: reinsurance premiums go up!

Natural catastrophes: Comparison 2023 (in bn. USD)

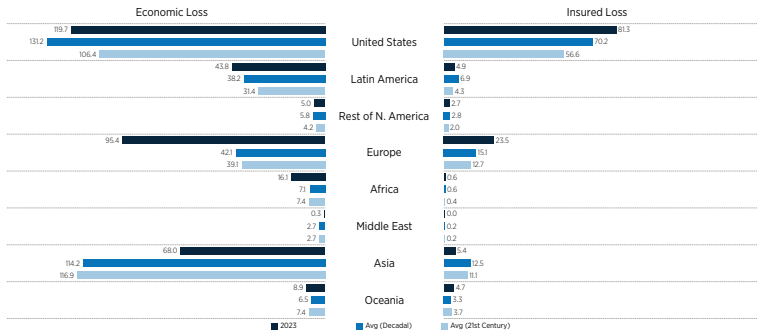
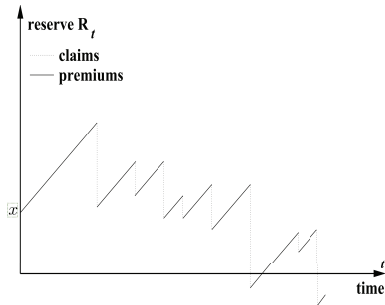


Figure 9: Regional economic and insured losses in 2023 versus recent history | Data and Graphic: Gallagher Re

Gallagher Re: NatCat & Climate Report 2023

- ▶ Climate Change: reinsurance premiums go up!
- ▶ **How to make natural catastrophe insurance attractive?**

Alternative (profitability) criterion:



B. de Finetti (1957)

Expected sum of discounted dividend payments until ruin

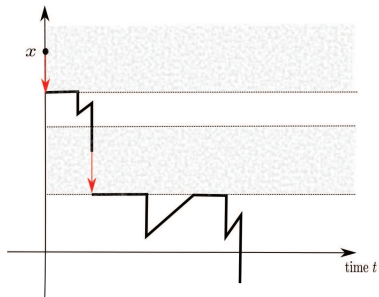
$$\mathbb{E}_x\left(\int_0^\tau e^{-\delta t} dD_t\right) \longrightarrow \text{maximize!}$$

Stochastic Control Problem:

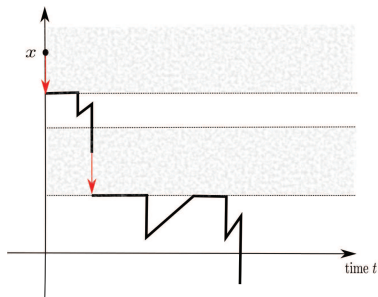
- Compound Poisson: e.g. Gerber (1969), Schmidli (2008), Azcue & Muler (2014)
- Diffusion: e.g. Gerber (1972), Jeanblanc-Piqué & Shiryaev (1994), Asmussen & Taksar (1997)

e.g. A. & Thonhauser (2009), Avanzi (2009)

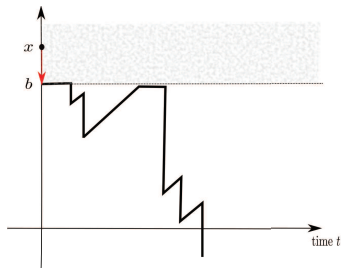
Optimal Strategy: Band Strategy



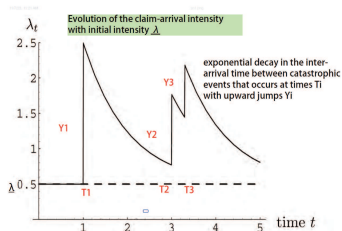
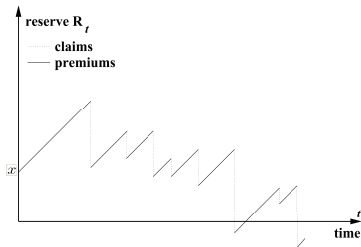
Optimal Strategy: Band Strategy



Diffusion, certain compound Poisson/Lévy processes: Barrier Strategy



A compound Cox model



$N(t)$... shot-noise Cox process:

$$R_t = x + p t - \sum_{n=1}^{N(t)} X_n$$

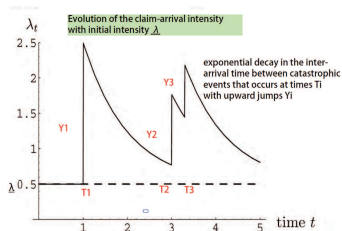
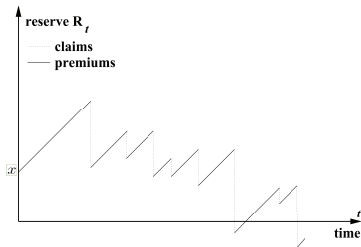
$$\lambda_t = \lambda_t^c + \sum_{k=1}^{\tilde{N}_t} Y_k e^{-d(t-T_k)}$$

with $\lambda_t^c = \underline{\lambda} + e^{-dt} (\lambda - \underline{\lambda})$, $d > 0$

$\tilde{N}_t = \#\{k : T_k \leq t\}$... Poisson process of constant intensity β

Dassios & Jang (2003), A. & Asmussen (2006), Pojer & Thonhauser (2023)

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Premium rate:

$$p = (1 + \eta) \mathbb{E}(X_n) \lim_{t \rightarrow \infty} \mathbb{E}(\Lambda_t/t) = (1 + \eta) \mathbb{E}(X_n)(\underline{\lambda} + \beta \mathbb{E}(Y_k)/d)$$

The optimal dividend problem

$\Pi_{x,\lambda}$: set of admissible dividend strategies $L = (L_t)_{t \geq 0}$:
non-decreasing, càdlàg, adapted, $L_0 \geq 0$ and
 $L_t \leq R_t$ for $t < \tau^L = \inf \{t \geq 0 : R_t - L_{t-} < 0\}$.

Two-dimensional stochastic control problem

$$V(x, \lambda) = \sup_{L \in \Pi_{x,\lambda}} \mathbb{E} \left(\int_{0-}^{\tau^L} e^{-\delta t} dL_t \right)$$

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Two-dimensional stochastic control problem

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Basic properties:

- ▶ $V(x, \lambda)$ non-decreasing in x , non-increasing in λ
- ▶ $V(x, \lambda)$ locally Lipschitz in x and in $\lambda > \underline{\lambda}$
- ▶ $V(x, \lambda) \leq v^{\underline{\lambda}}(x) \leq x + p/\delta$
- ▶ $\lim_{\lambda \rightarrow \infty} V(x, \lambda) = x$

Hamilton-Jacobi-Bellman equation

$$\max\{\mathcal{L}(V)(x, \lambda), 1 - V_x(x, \lambda)\} = 0, \quad x \geq 0, \lambda \geq \underline{\lambda} \quad (\otimes)$$

where

$$\begin{aligned} \mathcal{L}(V)(x, \lambda) = & \quad pV_x(x, \lambda) - d(\lambda - \underline{\lambda})V_\lambda(x, \lambda) - (\delta + \lambda + \beta)V(x, \lambda) \\ & + \lambda \int_0^x V(x - y, \lambda) dF_X(y) + \beta \int_0^\infty V(x, \lambda + z) dF_Y(z). \end{aligned}$$

Hamilton-Jacobi-Bellman equation

$$\max\{\mathcal{L}(V)(x, \lambda), 1 - V_x(x, \lambda)\} = 0, \quad x \geq 0, \lambda \geq \underline{\lambda} \quad (\otimes)$$

where

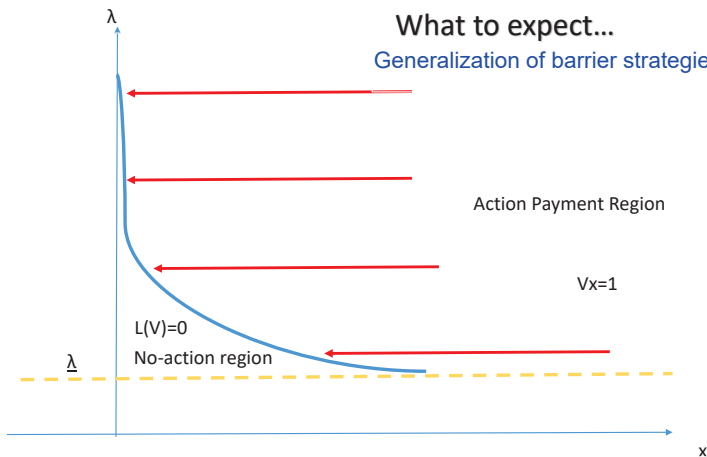
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Theorem: The optimal value function V is the smallest viscosity solution of $(\otimes)$ in $[0, \infty) \times [\underline{\lambda}, \infty)$ satisfying linear boundedness in x and $\lim_{\lambda \rightarrow \infty} V(x, \lambda) = x$.

- Verification Theorem
- $V(x, \lambda) = x - p/\delta + V(p/\delta, \lambda)$ for $x \geq p/\delta \quad \forall \lambda > \underline{\lambda}$

What to expect...

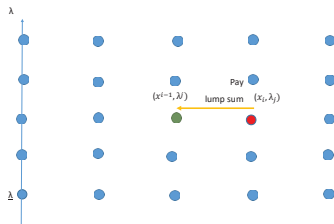
Generalization of barrier strategies



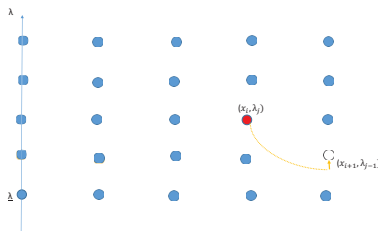
Free boundary problem - numerically very hard!

- ▶ **Approximate** by optimal strategies on fine two-dim. grid
- ▶ Uniform convergence of these strategies to V

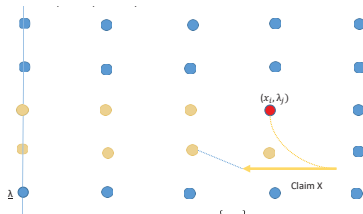
Finite grid



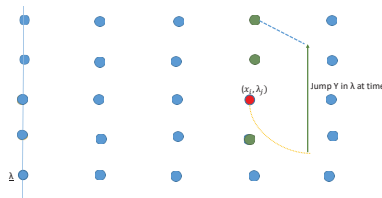
lump sum payment



no dividends until next grid point



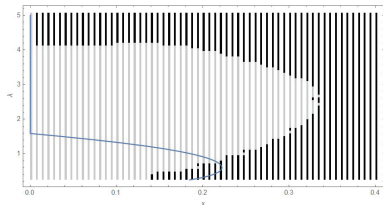
no dividends until next claim



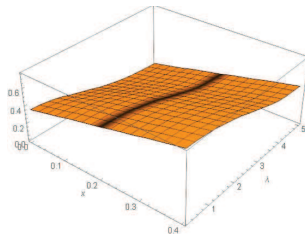
no dividends until next intensity
jump

Example 1: $X \sim \text{Exp}(10)$, $\underline{\lambda} = 1/4$, $Y \sim \text{Exp}(1/2)$, $\beta = 1/2$, $d = 7/10$

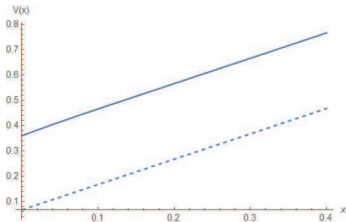
(halftime of intensity increase is 1 year), $\delta = 0.2$, $\eta = 0.2$ ($\lambda_{\text{av}} = 1.679$, so $p = 0.201$).



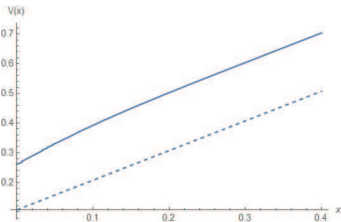
Action regions (dark) and non-action regions (light) of the optimal strategy as a function of λ and x



$V(x, \lambda)$



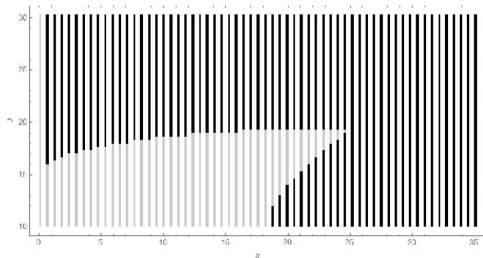
$V(x, \underline{\lambda})$ (solid) vs. $V_{\text{CL}}(x, \underline{\lambda})$ (dashed)



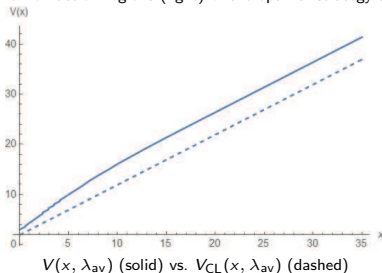
$V(x, \lambda_{\text{av}})$ (solid) vs. $V_{\text{CL}}(x, \lambda_{\text{av}})$ (dashed)

Example 2: $X \sim \text{Erl}(2, 1)$, $\underline{\lambda} = 10$, $Y \sim \text{Exp}(1/2)$, $\beta = 0.2$, $d = 0.2$, $\delta = 0.1$,
 $\eta = 0.07$ ($\lambda_{\text{av}} = 12$, so $p = 25.68$).

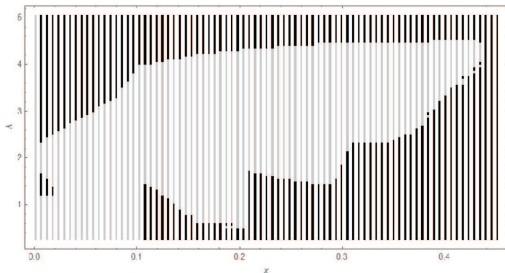
hom. Poisson: Optimal 2-band!



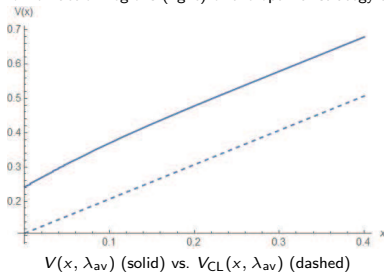
Action regions (dark) and non-action regions (light) of the optimal strategy as a function of λ and x



Example 3: Like Example 1, but with deterministic claim sizes: $F_X(x) = I_{[1/10, \infty)}$.



Action regions (dark) and non-action regions (light) of the optimal strategy as a function of λ and x



Conclusion

- ▶ New two-dimensional stochastic control problem
- ▶ Variability of claim intensity can be advantage!
- ▶ Potential for catastrophe insurance (IFRS, regulation?)

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Possible Extensions:

- ▶ Unknown intensity: filtering
- ▶ Non-stationarities (climate change!)
- ▶ Hawkes processes (cyber risk) etc.

Thank you for your attention!



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Expertise Center for Climate Extremes (ECCE) at UNIL

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