| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| | | |
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Model selection for common time series models

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> EcoDep Conference September 10, 2020

Model selection for common time series models

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3

Model selection problem

Assume that the observed trajectory (X_1, \ldots, X_n) is generated from a model m.

m belongs to a collection \mathcal{M} : for instance, a set of ARMA(p, q) and GARCH(p', q') processes for $0 \le p \le p_{\text{max}}$, $0 \le q \le q_{\text{max}}$, $0 \le p' \le p'_{\text{max}}$, $0 \le q' \le q'_{\text{max}}$

We would like to chose in \mathcal{M} , a "best" model for fitting the data (X_1, \ldots, X_n) .

For instance, if $p_{\max} = q_{\max} = p'_{\max} = q_{\max} = 9$, in the collection above, there is 200 possible models and we expect to recognize the true process

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| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| | | |
| | | |

Outline

1 Introduction

- 2 The model selection criterion
- 3 Asymptotic results
- 4 Some numerical Results

Model selection for common time series models

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3

< (T) >

| Introduction | The model selection criterion | Asymptotic results | Some numerical Results |
|--------------|-------------------------------|--------------------|------------------------|
| ••••• | | | |
| | | | |

Outline

1 Introduction

2 The model selection criterion

3 Asymptotic results

4 Some numerical Results

Model selection for common time series models

William KENGNE

CY Cergy Paris Université

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| Introduction 000000 | The model selection criterion | Asymptotic results | Some numerical Results |
|------------------------|-------------------------------|--------------------|------------------------|
| | | | |

Introduction

We consider the class

Class $\mathcal{AC}(M, f)$: A process $X = (X_t)_{t \in \mathbb{Z}}$ belongs to $\mathcal{AC}(M, f)$ if it satisfies:

$$X_t = Mig((X_{t-i})_{i\in\mathbb{N}^*}ig)\,\xi_t + fig((X_{t-i})_{i\in\mathbb{N}^*}ig) \,\,\, ext{for any}\,\,t\in\mathbb{Z};$$

where :

 $M, f : \mathbb{R}^{\infty} \to \mathbb{R}$ are measurable functions $(\xi)_{t \in \mathbb{Z}}$: sequence of zero-mean i.i.d. random variable satisfying $\mathbb{E}[\xi_0^2] = 1$

The existence of stationarity and ergodic solution in such models has been studied by Doukhan and Wintenberger (2008), see also Bardet and Wintenberger (2009).

| Introduction 000000 | The model selection criterion | Asymptotic results 00000 | Some numerical Results |
|------------------------|-------------------------------|-----------------------------|------------------------|
| | | | |

Introduction

Semiparametric setting :

The distribution of ξ_0 is unknown

 (X_1, \ldots, X_n) is a trajectory of a process $X = (X_t)_{t \in \mathbb{Z}}$ that belongs to $\mathcal{AC}(M_{\theta^*}, f_{\theta^*})$, with $\theta^* \in \Theta \subset \mathbb{R}^d$

 $M_{ heta^*}$, $f_{ heta^*}$ are known up to $heta^*$

 θ^* corresponds to the true model $m^* \in \mathcal{M}$; where \mathcal{M} is a finite collection of models.

Thus, we will consider in the sequel the class $\mathcal{AC}(M_{\theta}, f_{\theta})$ for $\theta \in \Theta$.

| Introduction 000000 | The model selection criterion | Asymptotic results 00000 | Some numerical Results |
|------------------------|-------------------------------|-----------------------------|------------------------|
| In the desired | | | |

The model selection setting :

Introduction

We will consider several models, which all are particular cases of $\mathcal{AC}(M_{\theta}, f_{\theta})$ with $\theta \in \Theta \subset \mathbb{R}^{d}$.

- a model m as a subset of $\{1, \ldots, d\}$ and denote |m| = #(m);
- $\Theta(m) = \{(\theta_i)_{1 \le i \le d} \in \mathbb{R}^d, \ \theta_i = 0 \text{ if } i \notin m\} \cap \Theta;$
- \mathcal{M} as a finite family of models, *i.e.* $\mathcal{M} \subset \mathcal{P}(\{1, \ldots, d\})$.

For all $m \in \mathcal{M}$, $m \in \mathcal{AC}(M_{\theta}, f_{\theta})$ when $\theta \in \Theta(m)$.

Our main aim is to select a model \widehat{m} (among the collection \mathcal{M}) which is "close" to m^* at least when n is large enough.

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| Introduction 000000 | The model selection criterion | Asymptotic results | Some numerical Results |
|------------------------|-------------------------------|--------------------|------------------------|
| | | | |

Example

$$\begin{cases} AR & \begin{cases} M_{\theta_{1}}^{(1)}((X_{t-i})_{i\in\mathbb{N}^{*}}) = \sigma \\ f_{\theta_{1}}^{(1)}((X_{t-i})_{i\in\mathbb{N}^{*}}) = \phi_{1}X_{t-1} + \dots + \phi_{p}X_{t-p} \end{cases} \\ \\ ARCH & \begin{cases} M_{\theta_{2}}^{(2)}((X_{t-i})_{i\in\mathbb{N}^{*}}) = \sqrt{a_{0} + a_{1}X_{t-1}^{2} + \dots + a_{q}X_{t-q}^{2}} \\ f_{\theta_{2}}^{(2)}((X_{t-i})_{i\in\mathbb{N}^{*}}) = 0 \end{cases} \\ \\ \implies \begin{cases} M_{\theta}((X_{t-i})_{i\in\mathbb{N}^{*}}) = \sqrt{\theta_{0} + \theta_{1}X_{t-1}^{2} + \dots + \theta_{q}X_{t-q}^{2}} \\ f_{\theta}((X_{t-i})_{i\in\mathbb{N}^{*}}) = \theta_{q+1}X_{t-1} + \dots + \theta_{q+p}X_{t-p} \end{cases} \end{cases} \end{cases}$$

Model selection for common time series models

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| Introduction 00000● | The model selection criterion | Asymptotic results 00000 | Some numerical Results |
|------------------------|-------------------------------|-----------------------------|------------------------|
| | | | |

Example

We could as well consider hierarchical or exhaustive families of models.

From the previous example, we can consider:

- a family M₁ such as M₁ = {{1}, {1,2},..., {1,..., q + 1}}: this family is the hierarchical one of ARCH processes with orders varying from 0 to q
- a family \mathcal{M}_2 such as $\mathcal{M}_2 = \mathcal{P}(\{1, \dots, p+q+1\})$: this family is the exhaustive one and contains as well the AR(2) process $X_t = \phi_2 X_{t-2} + \sigma \xi_t$ as the process $X_t = \phi_1 X_{t-1} + \phi_3 X_{t-3} + \xi_t \sqrt{\theta_0 + a_2 X_{t-2}^2}$.

э

| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| 0000 | | |
| | | |

Outline

1 Introduction

2 The model selection criterion

- 3 Asymptotic results
- 4 Some numerical Results

Model selection for common time series models

William KENGNE

CY Cergy Paris Université

3

| Introduction | The model selection criterion | Asymptotic results | Some numerical Results |
|--------------|-------------------------------|--------------------|------------------------|
| 000000 | 0000 | 00000 | |
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Consider a model $m \in \mathcal{M}$ and the class $\mathcal{AC}(M_{\theta}, f_{\theta})$ for $\theta \in \Theta(m) \subset \Theta \subset \mathbb{R}^{d}$.

Assume that (X_1, \dots, X_n) is observed.

Consider the approximated quasi (log)likelihood given (up to a constant) for all $\theta \in \Theta(m)$ by

$$\widehat{L}_n(\theta) := -\frac{1}{2} \sum_{t=1}^n \widehat{q}_t(\theta) , \text{ with } \widehat{q}_t(\theta) := \frac{(X_t - \widehat{f}_{\theta}^t)^2}{\widehat{H}_{\theta}^t} + \log(\widehat{H}_{\theta}^t)$$
(2)

where
$$\widehat{f}_{\theta}^{t} = f_{\theta}(X_{t-1}, X_{t-2}, \cdots, X_{1}, 0, \cdots),$$

 $\widehat{M}_{\theta}^{t} = M_{\theta}(X_{t-1}, X_{t-2}, \cdots, X_{1}, 0, \cdots), \ \widehat{H}_{\theta}^{t} = (\widehat{M}_{\theta}^{t})^{2}.$

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William KENGNE

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| Introduction 000000 | The model selection criterion | Asymptotic results | Some numerical Results |
|------------------------|-------------------------------|--------------------|------------------------|
| The QMLE | | | |

The "best" parameter associated to the model m if defined by,

 $\theta^*(m) = \operatorname*{argmin}_{\theta \in \Theta(m)} \mathbb{E}[q_0(\theta)].$

According to Bardet *et al.* (2020), $\theta^*(m)$ exists and it is unique under some identifiability assumptions.

When $m = m^*$, we have $\theta^*(m^*) = \theta^*$.

For any $m \in \mathcal{M}$, the QMLE of $\theta^*(m)$ is given by

$$\widehat{\theta}(m) = \underset{\theta \in \Theta(m)}{\operatorname{argmax}} \widehat{L}_n(\theta).$$
(3)

Model selection for common time series models

3

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| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| 0000 | | |
| | | |

The criterion

The selection of the "best" model \widehat{m} among the collection \mathcal{M} is performed by minimizing the penalized contrast

$$\widehat{C}(m) = -2\widehat{L}_n(\widehat{\theta}(m)) + |m|\kappa_n,$$

that is

$$\widehat{m} = \operatorname*{argmin}_{m \in \mathcal{M}} \widehat{C}(m),$$

where

- $(\kappa_n)_n$ is a sequence of a regularization parameter
- |m| denotes the dimension of the model m, i.e. the cardinal of m, subset of {1,..., d}, which is also the number of estimated components of θ (the others are fixed to zero).
 The procedure is consistent when

$$\mathbb{P}(\widehat{m}=m^*) \xrightarrow[n \to \infty]{} 1.$$

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| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| | 00000 | |
| | | |

Outline

1 Introduction

2 The model selection criterion

3 Asymptotic results

4 Some numerical Results

Model selection for common time series models

William KENGNE

CY Cergy Paris Université

3

| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| | 0000 | |
| | | |

Some Lipschitz-type conditions

For any compact subset $\mathcal{K} \subset \Theta$ and for $\Psi = f$ or M and k = 0, 1, 2, define

Assumption $(A_k(\Psi, \mathcal{K}))$: $\|\frac{\partial^k \Psi_{\theta}(0)}{\partial \theta^k}\|_{\mathcal{K}} < \infty$ and there exists a non-negative sequence $(\alpha_i^{(k)}(\Psi, \mathcal{K}))_i$ such that $\forall x, y \in \mathbb{R}^{\mathbb{N}}$,

$$\|\frac{\partial^k \Psi_{\theta}(x)}{\partial \theta^k} - \frac{\partial^k \Psi_{\theta}(y)}{\partial \theta^k}\|_{\mathcal{K}} \leq \sum_{i=1}^{\infty} \alpha_i^{(k)}(\Psi, \mathcal{K})|x_i - y_i|$$

with
$$\sum_{i=1}^{\infty} \alpha_i^{(0)}(\Psi, \mathcal{K}) < 1$$
 and $\sum_{i=1}^{\infty} \alpha_i^{(k)}(\Psi, \mathcal{K}) < \infty$ for $k = 1, 2$.

Model selection for common time series models

3

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| Introduction 000000 | The model selection criterion | Asymptotic results | Some numerical Results |
|------------------------|-------------------------------|--------------------|------------------------|
| | | | |

The results

In the sequel, we assume that : $\kappa_n \xrightarrow[n \to \infty]{} \infty$, $\kappa_n/n \xrightarrow[n \to \infty]{} 0$, $\mathbb{E}|\xi_0|^r < \infty$ for some $r \ge 3$ and

$$\sum_{k\geq 1}\frac{1}{\kappa_k}\sum_{j\geq k}\alpha_j^{(0)}(f_\theta,\Theta)+\alpha_j^{(0)}(M_\theta,\Theta)+\alpha_j^{(1)}(f_\theta,\Theta)+\alpha_j^{(1)}(M_\theta,\Theta)<\infty.$$

Consistency:

Theorem

Under some regular conditions, including the above Lipschitz-type conditions on f_θ and M_θ :

1
$$P(\widehat{m} = m^*) \xrightarrow[n \to \infty]{} 1$$

2 $\widehat{\theta}(\widehat{m}) \xrightarrow[n \to \infty]{} \theta^*$

3

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| Introduction 000000 | The model selection criterion | Asymptotic results | Some numerical Results |
|------------------------|-------------------------------|--------------------|------------------------|
| | | | |

The results

Asymptotic normality of the selected model:

Theorem

Under some regular conditions, including the above Lipschitz-type conditions on f_θ and M_θ :

$$\sqrt{n} \left(\left(\widehat{\theta}(\widehat{m}) \right)_{i} - \left(\theta^{*} \right)_{i \in m^{*} n \to \infty} \mathcal{N}_{|m^{*}|} \left(0, F(\theta^{*}, m^{*})^{-1} G(\theta^{*}, m^{*}) F(\theta^{*}, m^{*})^{-1} \right)$$

where

$$ig(F(heta^*,m^*)ig)_{i,j} = \mathbb{E}\Big[rac{\partial^2 q_0(heta^*)}{\partial heta_i \partial heta_j}\Big]$$
 and
 $(G(heta^*,m^*))_{i,j} = \mathbb{E}\Big[rac{\partial q_0(heta^*)}{\partial heta_i}rac{\partial q_0(heta^*)}{\partial heta_j}\Big]$ for $i,j\in m^*$.

| Introduction 000000 | The model selection criterion | Asymptotic results 0000● | Some numerical Results |
|------------------------|-------------------------------|-----------------------------|------------------------|
| The results | | | |

The conditions on the Lipschitz-type coefficients show that :

the BIC procedure (with $\kappa_n = \log n$) is consistent in the case of AR(*p*), ARMA, ARCH(*q*), GARCH, ARMA-GARCH, ···

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| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| | | •0000000 |
| | | |

Outline

1 Introduction

2 The model selection criterion

3 Asymptotic results

4 Some numerical Results

Model selection for common time series models

William KENGNE

CY Cergy Paris Université

2

| Introduction 000000 | The model selection criterion | Asymptotic results 00000 | Some numerical Results |
|------------------------|-------------------------------|-----------------------------|------------------------|
| | | | |

Simulation results

We consider the following DGP as "true" models m^* :

- **1** Model 1, AR(2): $X_t = 0.4X_{t-1} + 0.4X_{t-2} + \xi_t$;
- **2** Model 2, ARMA(1,1): $X_t = 0.3X_{t-1} + \xi_t + 0.5\xi_{t-1}$;
- **3** Model 3, ARCH(2): $X_t = \xi_t \sqrt{0.2 + 0.4X_{t-1}^2 + 0.2X_{t-2}^2};$
- 4 Model 4, GARCH(1, 1): $X_t = \sigma_t \xi_t$, with $\sigma_t^2 = 0.2 + 0.3X_{t-1}^2 + 0.5\sigma_{t-1}^2$.

The collection of the competing models is : $\mathcal{M} = \{ARMA(p,q) \text{ or } GARCH(p',q') \text{ with } 0 \le p,q,p' \le 5, 1 \le q' \le 5\}$

There are 66 candidate models.

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| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| | | 0000000 |
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Simulation results

| | n | | 100 | | | 500 | | | 1000 | | | 2000 | |
|----|---|----------|------------|----------------------|----------|------------|----------------------|-----------------------|------------|----------------------|-----------------------|------------|----------------------|
| | | $\log n$ | \sqrt{n} | $\widehat{\kappa}_n$ | $\log n$ | \sqrt{n} | $\widehat{\kappa}_n$ | $\left \log n\right $ | \sqrt{n} | $\widehat{\kappa}_n$ | $\left \log n\right $ | \sqrt{n} | $\widehat{\kappa}_n$ |
| | W | 21.4 | 32.3 | 18.4 | 1.7 | 0.8 | 0.9 | 0.8 | 0.1 | 0.1 | 0.2 | 0 | 0 |
| M1 | T | 74.2 | 67.6 | 79.7 | 97.2 | 99.2 | 99.1 | 98.2 | 99.9 | 99.9 | 99.2 | 100 | 100 |
| | 0 | 4.4 | 0.1 | 1.9 | 1.1 | 0 | 0 | 1.0 | 0 | 0 | 0.6 | 0 | 0 |
| | W | 30.4 | 57.7 | 28.0 | 4.8 | 4.2 | 4.0 | 0.7 | 0.3 | 0.3 | 0.4 | 0 | 0 |
| M2 | T | 64.1 | 42.1 | 67.3 | 93.6 | 95.8 | 95.8 | 98.2 | 99.7 | 99.6 | 99.2 | 100 | 100 |
| | 0 | 5.5 | 0.2 | 4.7 | 1.6 | 0 | 0.2 | 1.1 | 0 | 0.1 | 0.4 | 0 | 0 |
| | W | 76.1 | 90.8 | 53.5 | 27.3 | 67.1 | 18.0 | 14.0 | 41.5 | 13.3 | 4.6 | 12.0 | 4.6 |
| M3 | Т | 23.8 | 9.2 | 39.8 | 72.7 | 32.9 | 79.9 | 85.9 | 58.5 | 86.7 | 95.4 | 88.0 | 95.4 |
| | 0 | 0.1 | 0 | 6.7 | 0 | 0 | 2.1 | 0.1 | 0 | 0 | 0 | 0 | 0 |
| | W | 83.8 | 94.3 | 73.4 | 22.1 | 61.5 | 20.4 | 5.8 | 31.3 | 5.7 | 1.8 | 6.2 | 0.7 |
| M4 | T | 15.9 | 5.7 | 21.6 | 77.5 | 38.5 | 75.9 | 93.2 | 68.7 | 92.6 | 98.0 | 93.8 | 99.3 |
| | 0 | 0.3 | 0 | 5.0 | 0.4 | 0 | 3.7 | 1.0 | 0 | 1.7 | 0.2 | 0 | 0 |

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Air quality : the level of cleanliness of the air

Air pollution is probably one of the first environmental (ecological) concerns of this century

Due to the human activities, the air is degraded by a wide variety of pollutants, including PM.

PM stands for particulate matter : the term for a mixture of solid particles and liquid droplets found in the air

We consider daily observations of PM10 (with diameters \leq 10 micrometers) at Marseille Kaddouz station from January 1, 2018 to November 30, 2019.

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| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| | | 0000000 |
| | | |

The data



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| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| | | 00000000 |
| | | |

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| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| | | 00000000 |
| | | |

The selection results:

| | $\kappa_n = \log(n)$ | $\kappa_n = \sqrt{n}$ | $\kappa_n = \widehat{\kappa}_n$ |
|---|----------------------|-----------------------|---------------------------------|
| m | ARMA(1,2) | ARMA(1,1) | ARMA(1,1) |

The Portmanteau test applied to these models shows that ARMA(1,2) is more suitable.

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| The model selection criterion | Asymptotic results | Some numerical Results |
|-------------------------------|--------------------|------------------------|
| | | 0000000 |
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THANK YOU FOR YOUR ATTENTION.

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2

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